

Controlling Airport Runway Queues Under Variable Conditions

Daniel Moscoe

Modeling and Simulation (DATA 604)

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[Colab](#)

Pushback control

- Planes burn fuel and generate emissions in the runway queue.
- A *pushback control scheme* controls when planes push back from the gate and enter the runway queue.
- A good pushback control scheme:
 - Ensures the runway is fully utilized;
 - Minimizes the length of the runway queue;
 - Thereby reduces fuel burn and emissions of planes waiting in runway queue.

Varieties of pushback control

- ***None***

- All planes advance to runway queue as soon as they request pushback from the gate.

- ***Naïve***

- For each time step, planes cleared to enter runway queue =
total scheduled departures per day / time steps per day

- ***Smart***

- Planes cleared to enter runway queue =
runway capacity at $t + 2$ less planes already waiting on runway (Simaiakis et al.)

Pushback control depends on dubious schedules

- Naïve pushback control requires total expected departures for day.
- Smart pushback control requires runway capacity 2 timesteps ahead.
- ***What if actual events at the gate and runway deviate from schedules?***

Simulation question

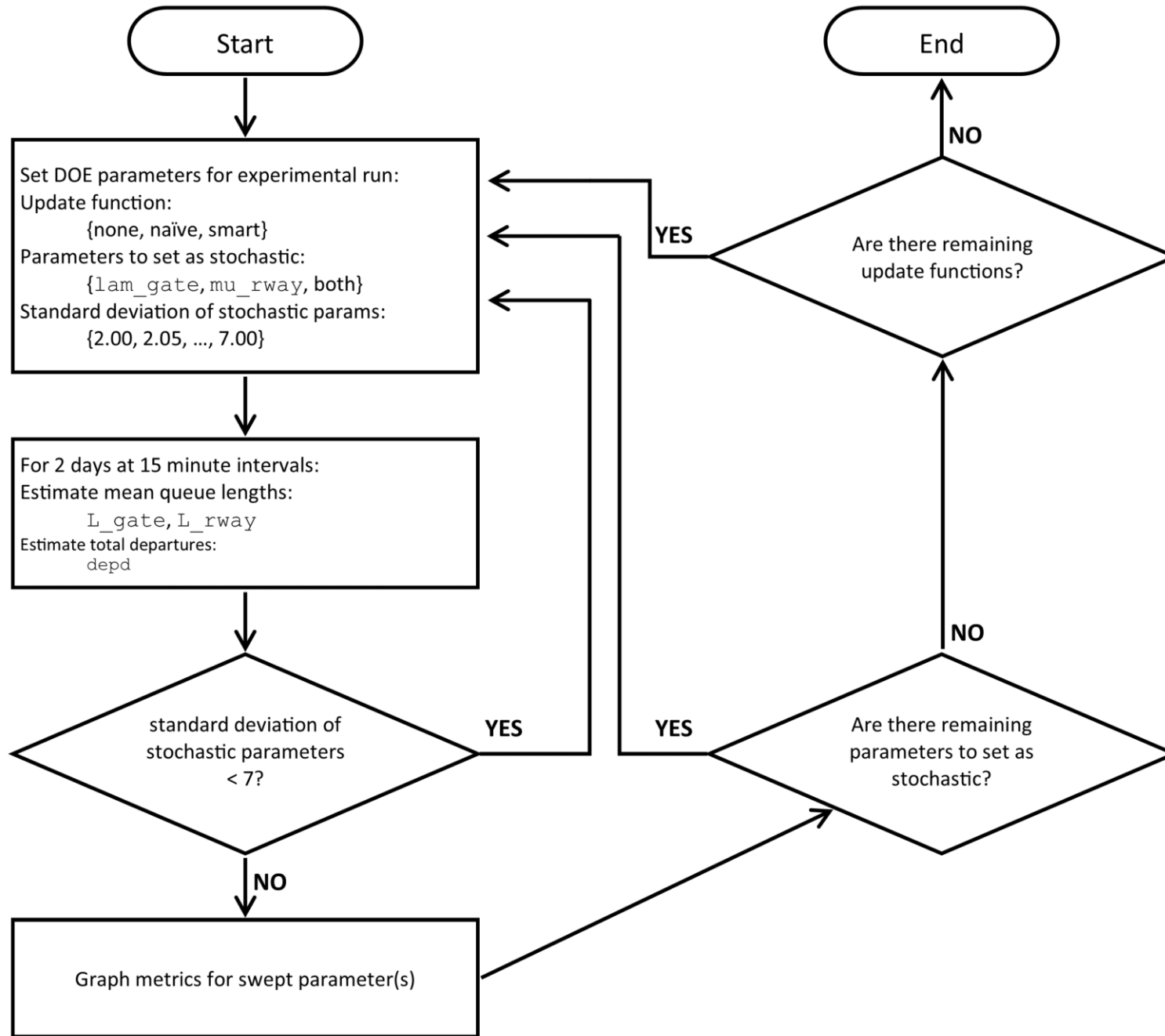
Given that events at an airport can unexpectedly deviate from their schedules, what is the optimal pushback rate control scheme?

How can events deviate from schedules?

- The number of planes requesting pushback from the gate (== entry into the gate queue) can unexpectedly deviate from the schedule.
 - Denoted λ_g , lam_gate.
- The runway capacity can unexpectedly deviate from the schedule.
 - Denoted μ_r , mu_rway.
- Both λ_g and μ_r can unexpectedly deviate.

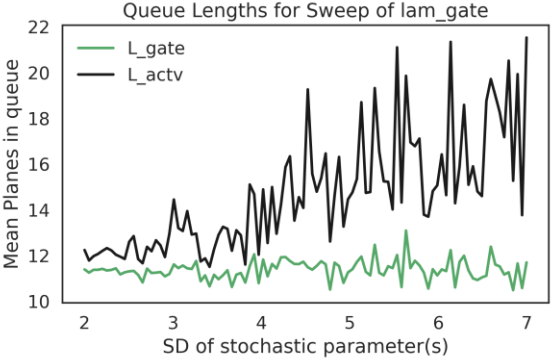
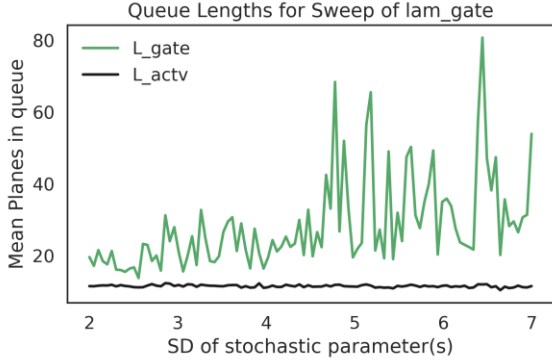
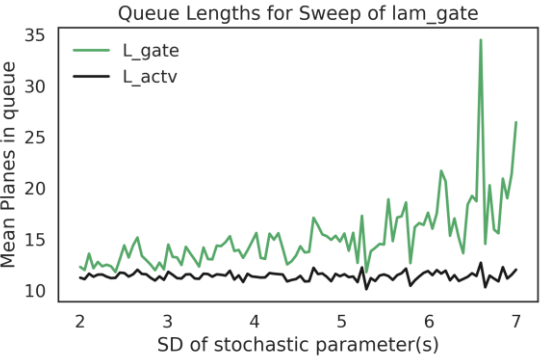
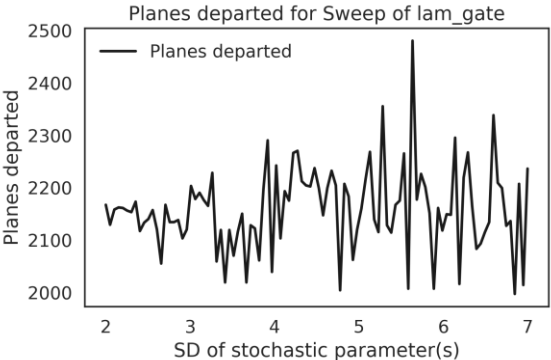
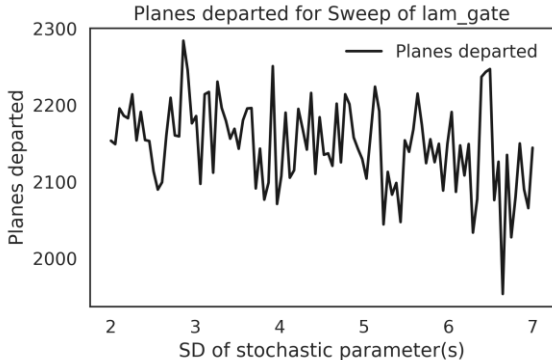
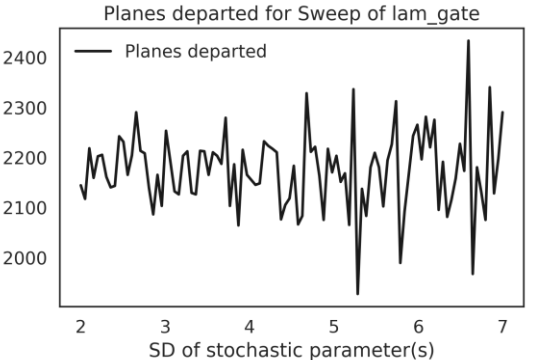
Modeling deviation from schedule

1. Choose a parameter allowed to deviate (λ_g or μ_r or both).
2. Choose a standard deviation in $\{2, 2.05, 2.10, \dots, 7\}$.
3. Look up scheduled parameter value for $t + 1$.
4. Build a normal distribution with:
 - mean = scheduled parameter value for $t + 1$,
 - sd = as chosen in step 2.
5. Sample 1 integer from this distribution.
6. Set the parameter at $t + 1$ equal to the value from 5.



Results

As deviation from pushback schedule increases, smart control performs best.

	<i>No pushback control</i>	<i>Naïve pushback control</i>	<i>Smart pushback control</i>
<i>Queue lengths</i>	 <p>Queue Lengths for Sweep of lam_gate</p> <p>Y-axis: Mean Planes in queue (10-22)</p> <p>X-axis: SD of stochastic parameter(s) (2-7)</p> <p>Legend: L_gate (green), L_actv (black)</p>	 <p>Queue Lengths for Sweep of lam_gate</p> <p>Y-axis: Mean Planes in queue (20-80)</p> <p>X-axis: SD of stochastic parameter(s) (2-7)</p> <p>Legend: L_gate (green), L_actv (black)</p>	 <p>Queue Lengths for Sweep of lam_gate</p> <p>Y-axis: Mean Planes in queue (10-35)</p> <p>X-axis: SD of stochastic parameter(s) (2-7)</p> <p>Legend: L_gate (green), L_actv (black)</p>
<i>Total planes departed</i>	 <p>Planes departed for Sweep of lam_gate</p> <p>Y-axis: Planes departed (2000-2500)</p> <p>X-axis: SD of stochastic parameter(s) (2-7)</p> <p>Legend: Planes departed (black)</p>	 <p>Planes departed for Sweep of lam_gate</p> <p>Y-axis: Planes departed (2000-2300)</p> <p>X-axis: SD of stochastic parameter(s) (2-7)</p> <p>Legend: Planes departed (black)</p>	 <p>Planes departed for Sweep of lam_gate</p> <p>Y-axis: Planes departed (2000-2400)</p> <p>X-axis: SD of stochastic parameter(s) (2-7)</p> <p>Legend: Planes departed (black)</p>

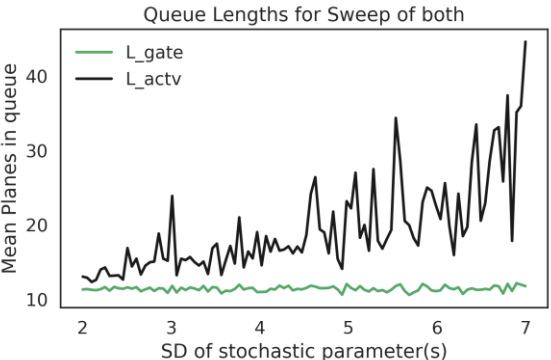
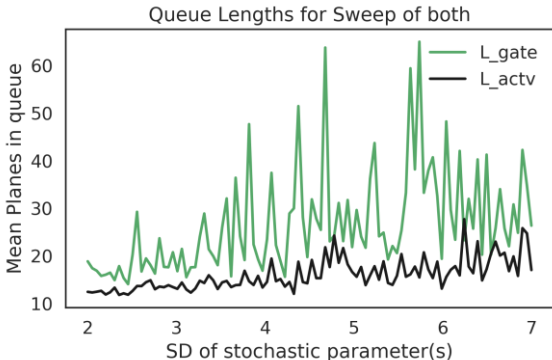
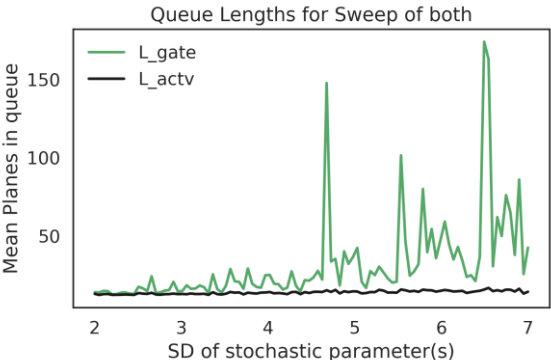
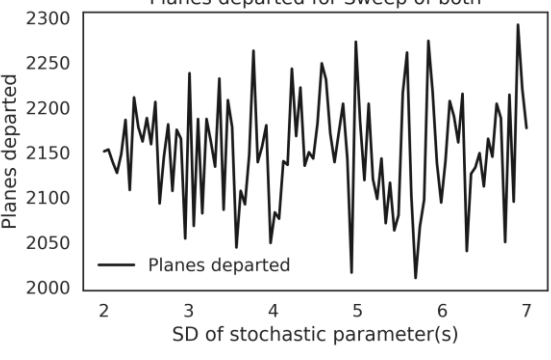
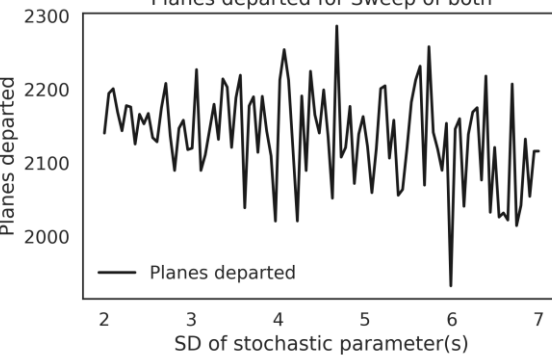
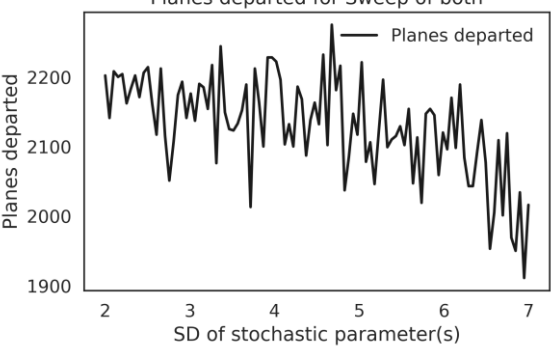
Results

***When deviation from scheduled runway capacity is low, smart control performs best.
As deviation from scheduled runway capacity increases, naïve control performs best.***

	<i>No pushback control</i>	<i>Naïve pushback control</i>	<i>Smart pushback control</i>
<i>Queue lengths</i>	<p>Queue Lengths for Sweep of mu_actv</p> <p>Mean Planes in queue</p> <p>SD of stochastic parameter(s)</p> <p>Legend: L_gate (green), L_actv (black)</p>	<p>Queue Lengths for Sweep of mu_actv</p> <p>Mean Planes in queue</p> <p>SD of stochastic parameter(s)</p> <p>Legend: L_gate (green), L_actv (black)</p>	<p>Queue Lengths for Sweep of mu_actv</p> <p>Mean Planes in queue</p> <p>SD of stochastic parameter(s)</p> <p>Legend: L_gate (green), L_actv (black)</p>
<i>Total planes departed</i>	<p>Planes departed for Sweep of mu_actv</p> <p>Planes departed</p> <p>SD of stochastic parameter(s)</p>	<p>Planes departed for Sweep of mu_actv</p> <p>Planes departed</p> <p>SD of stochastic parameter(s)</p>	<p>Planes departed for Sweep of mu_actv</p> <p>Planes departed</p> <p>SD of stochastic parameter(s)</p>

Results

With significant deviation from both schedules, naïve control performs best.

	<i>No pushback control</i>	<i>Naïve pushback control</i>	<i>Smart pushback control</i>
<i>Queue lengths</i>	 <p>Queue Lengths for Sweep of both</p> <p>Mean Planes in queue</p> <p>SD of stochastic parameter(s)</p> <p>Legend: L_gate (green), L_actv (black)</p>	 <p>Queue Lengths for Sweep of both</p> <p>Mean Planes in queue</p> <p>SD of stochastic parameter(s)</p> <p>Legend: L_gate (green), L_actv (black)</p>	 <p>Queue Lengths for Sweep of both</p> <p>Mean Planes in queue</p> <p>SD of stochastic parameter(s)</p> <p>Legend: L_gate (green), L_actv (black)</p>
<i>Total planes departed</i>	 <p>Planes departed for Sweep of both</p> <p>Planes departed</p> <p>SD of stochastic parameter(s)</p>	 <p>Planes departed for Sweep of both</p> <p>Planes departed</p> <p>SD of stochastic parameter(s)</p>	 <p>Planes departed for Sweep of both</p> <p>Planes departed</p> <p>SD of stochastic parameter(s)</p>

Discussion

- This simulation assumes that mean runway capacity slightly exceeds mean pushback rate from gate.
 - What if we varied mean runway capacity? Would this help accommodate greater deviations from schedules?
 - Would increased runway capacity (tighter schedules, greater reliance on technology) lead to greater deviations from schedules?

Works cited

- Badrinath, Sandeep, and Hamsa Balakrishnan. "Control of a non-stationary tandem queue model of the airport surface." 2017 American Control Conference (ACC). IEEE, 2017.
- Simaiakis, Ioannis, et al. "Demonstration of reduced airport congestion through pushback rate control." Transportation Research Part A: Policy and Practice 66 (2014): 251-267.